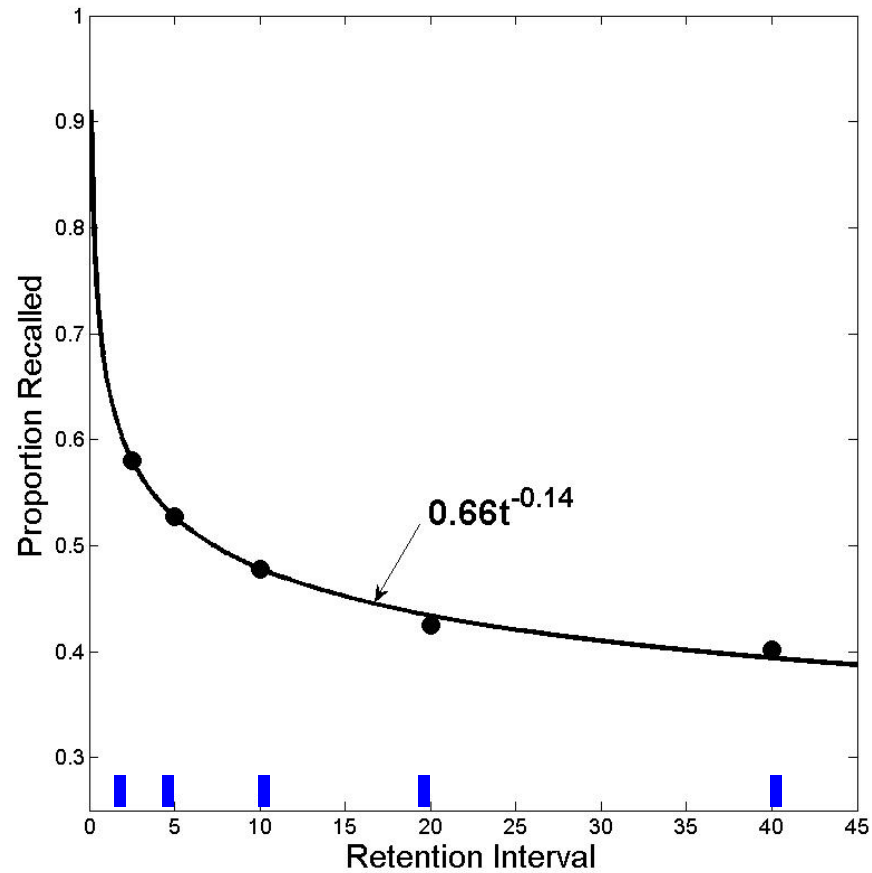


Optimal Experiment Design for Model Discrimination

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Australian Mathematical Psychology Conference (AMPC2009)
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Wixted and Ebbesen (1991) Experiment



Experimental Design:

$(t_1, t_2, t_3, t_4, t_5) = (2.5, 5, 10, 20, 40)$ (geometric design)

The Issue

- A goal of experimentation is to **distinguish between models**
- **Experimental design** relies on experimenter knowledge and intuitions about the models and experimental setup (stimuli, task, presentation schedule)
- With formal models, it should be possible to assist in this enterprise by identifying **designs that best discriminate** between them
- This is achieved by **optimizing the values of a chosen independent variable**

Formal Definition of Design Optimization Problem

An optimal design, intuitively, should **maximize extent of model dissimilarity** between models (Atkinson & Donev, 1992), formally,

- $d^* = \operatorname{argmax}_{d \in D} \{U(d)\}$
- $U(d) = \sum_{m=1}^K p(m) \iint u(d, y_m, \theta_m) p(y_m | \theta_m, d) p(\theta_m | d) dy_m d\theta_m$

$$(e.g., u(d, y_m, \theta_m) = \sum_{k \neq m}^K SSE(y_m, prd_k))$$

The $U(d)$ represents the **expected (i.e., average) utility** of a design d , where the expectation is taken over all the unknowns: models under consideration, model parameters, and possible experimental observations.

Finding the optimal design d^* , however, is a nontrivial undertaking due to the requirements of **optimization** and high dimensional **integration**.

Design Optimization via Density Simulation

Following Muller (1999) and Muller, Sanso & de Iorio (2004), we adopt a simulation-based Bayesian approach to design optimization.

The **Bayesian “trick”** is to treat d as a random variable, to view $U(d)$ as a density over design space, and to define an artificial distribution $h(\cdot)$ as

$$h(d, y_{m's}, \theta_{m's}) = \alpha \left[\sum_{m=1}^K p(m) u(d, y_m, \theta_m) \right] \prod_{m=1}^K p(y_m | \theta_m, d) p(\theta_m | d)$$

The marginal distribution $h(d)$ obtained after integrating out $y_{m's}$ and $\theta_{m's}$ turns out to be equal to $U(d)$, up to a proportionality constant,

$$\begin{aligned} h(d) &= \int \cdots \int h(d, y_{m's}, \theta_{m's}) dy_1 \cdots dy_K d\theta_1 \cdots d\theta_K \\ &= \alpha U(d) \end{aligned}$$

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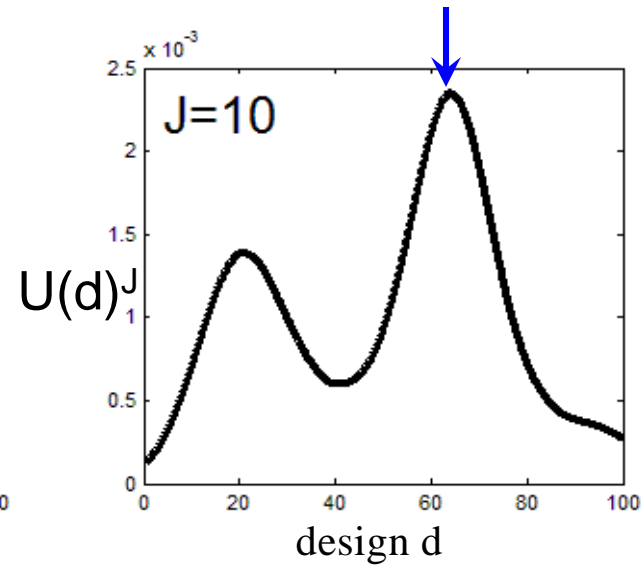
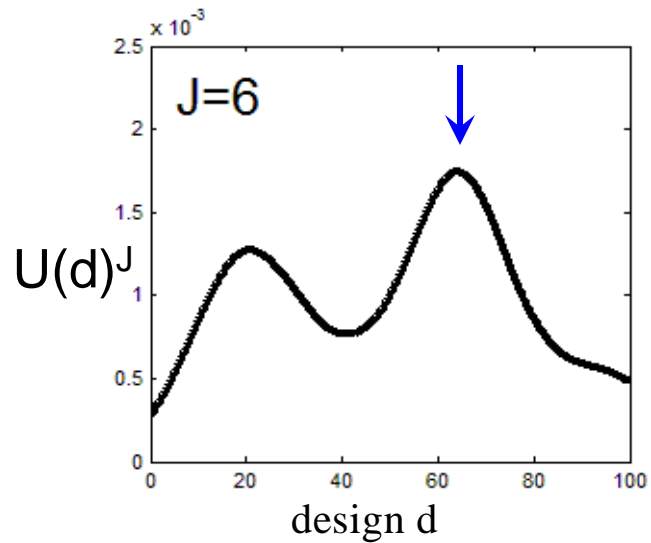
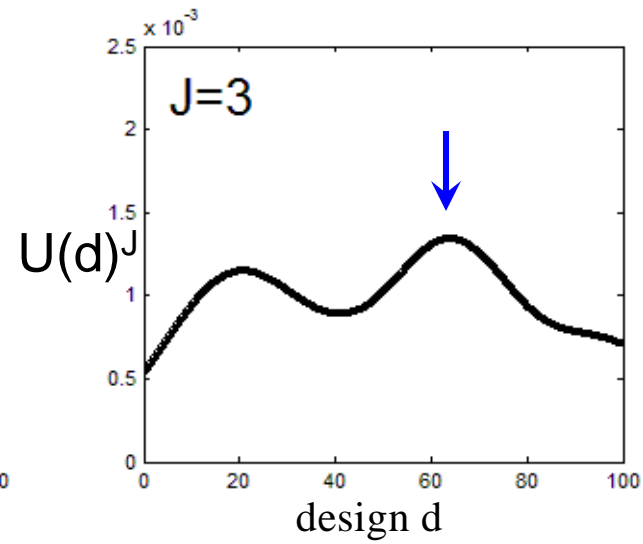
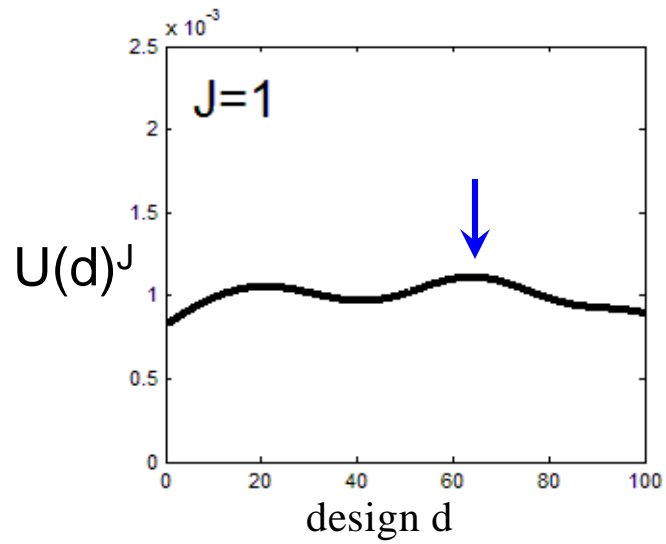
To improve computational efficiency, we **augment the artificial distribution** with **J** (e.g., =10) independent samples of $y_{m's}$ and $\theta_{m's}$ given a fixed d as follows

$$H_J(d, y_{mj's}, \theta_{mj's}) = \alpha_J \prod_{j=1}^J h(d, y_{mj's}, \theta_{mj's})$$

Marginalizing the above density $H_J(\cdot)$ over all $y_{mj's}$ and $\theta_{mj's}$ then yields

$$H_J(d) = \alpha_J U(d)^J$$

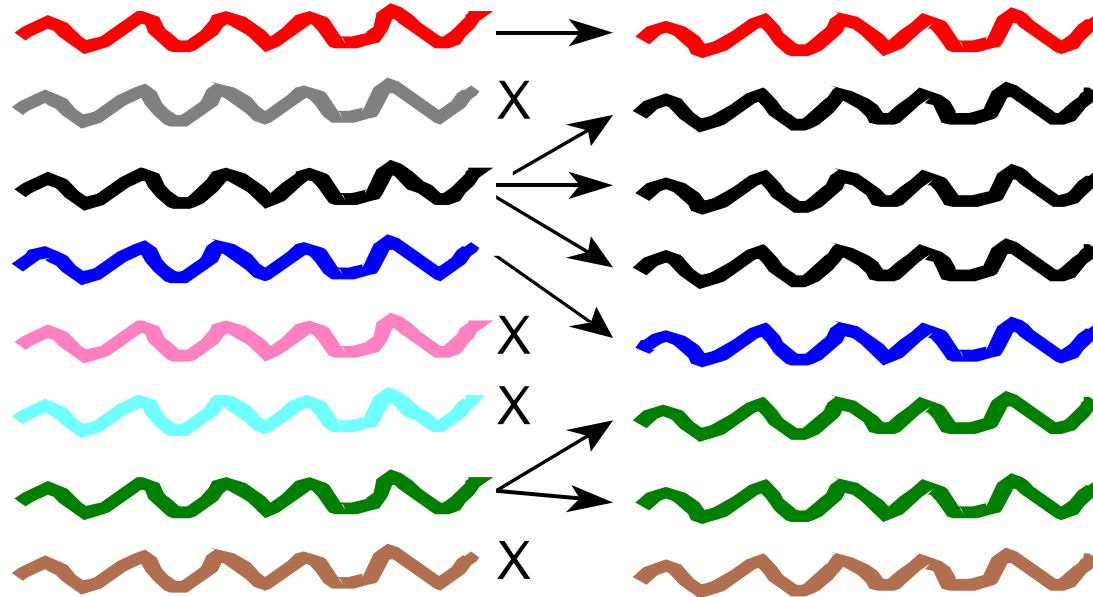
Optimization via “Sharpening-up”



Density Simulation via Sequential Monte Carlo (SMC)

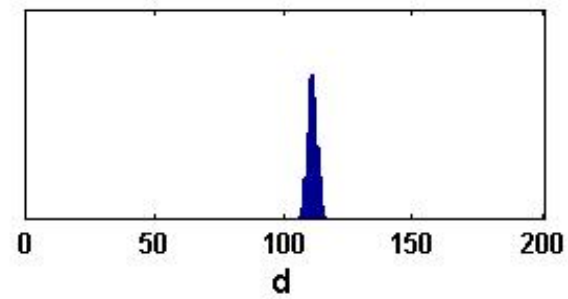
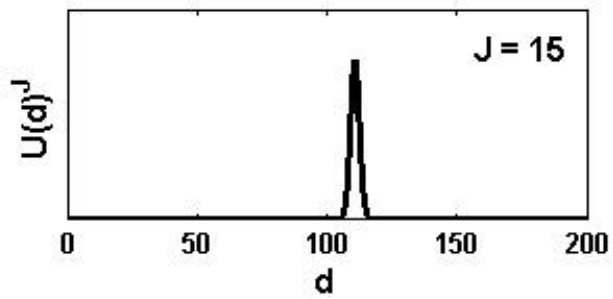
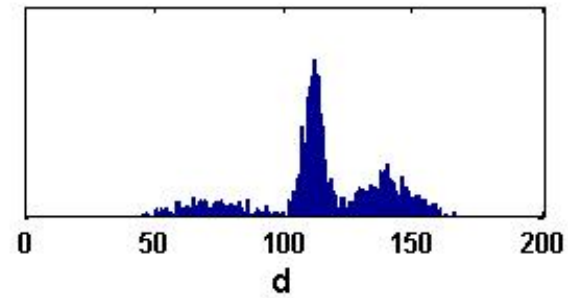
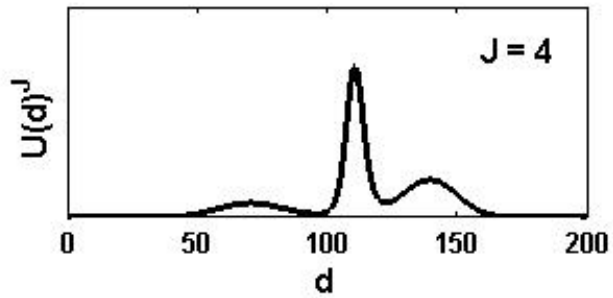
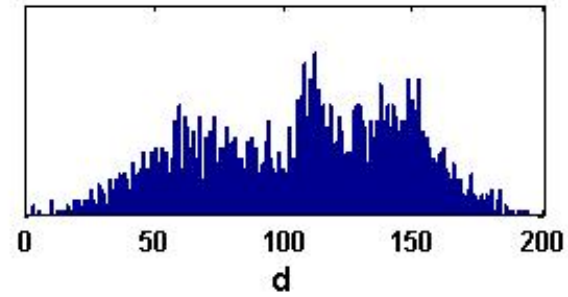
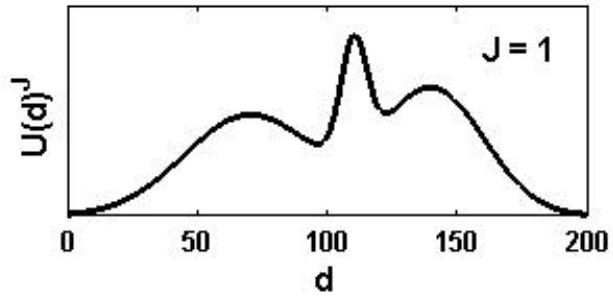
(Amzal, Bois, Parent, Robert, 2006; Doucet, de Freitas & Gordon, 2001)

SMC (or particle filter) is the machinery used in the sampling scheme. It consists of a *population* of “parallel-running & interacting” MCMC chains, called *particles*, that get eliminated or multiplied according to an evolutionary process.



Target density

SMC samples



Optimal Designs for Discriminating Retention Models

A central issue in memory research is to determine the exact course of forgetting over time. Of the dozens of retention functions, the following two have received considerable attention:

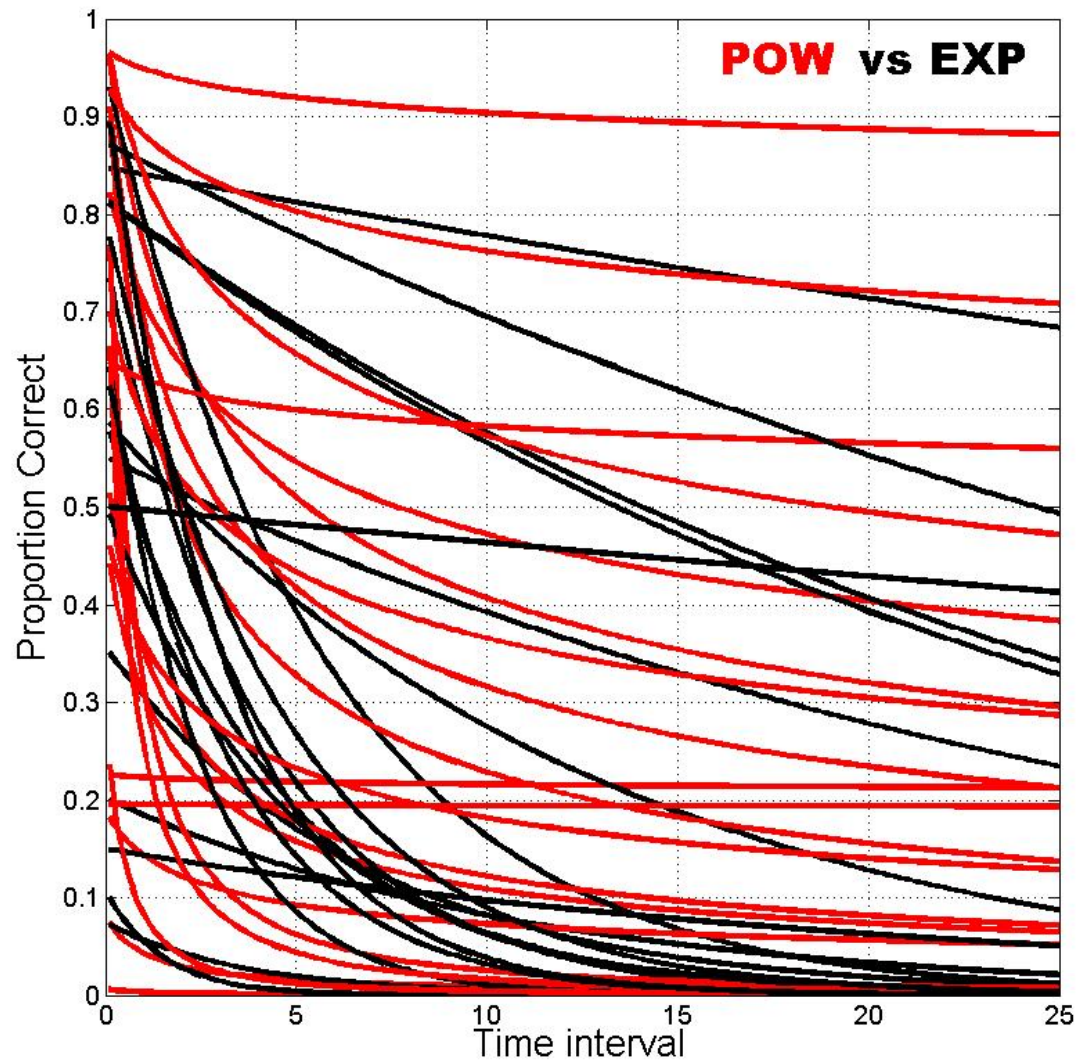
Power model (POW): $p_i = a(t_i + 1)^{-b}$

Exponential model (EXP): $p_i = a \exp(-bt_i)$

where p_i is the proportion of correct recall given retention time t_i and a and b are two parameters.

Design Optimization (DO) Problem:

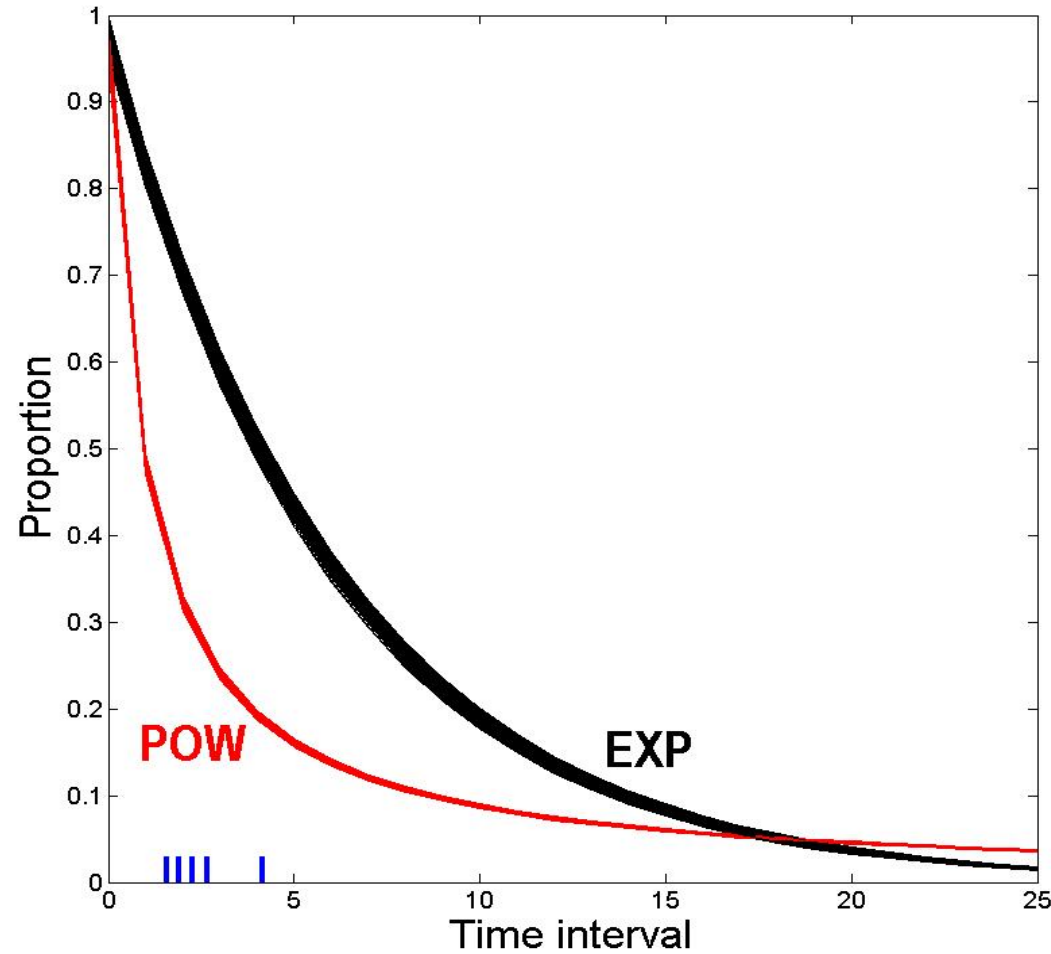
The problem is to find a design $d = \{t_1, \dots, t_N\}$ consisting of N time intervals that best discriminates the two models.



POW: $p = a(t+1)^{-b}$ ($0 < a < 1; 0 < b < 3$)

EXP: $p = ae^{-bt}$ ($0 < a < 1; 0 < b < 3$)

Intuitive Design Optimization



Restricted
parameter ranges

$$\text{POW: } p = a(t+1)^{-b} \quad (0.95 < a < 1; 1.00 < b < 1.01)$$

$$\text{EXP: } p = ae^{-bt} \quad (0.95 < a < 1; 0.16 < b < 0.17)$$

Encorporating Model Selection into Design Optimization

Model Recovery Rate as Utility Function:

Under this utility, the goal is to identify a design that maximizes the expected model recovery rate between two models, A and B, averaged across observations and parameters:

$$U(d) = E[I_A(d) + I_B(d)]$$

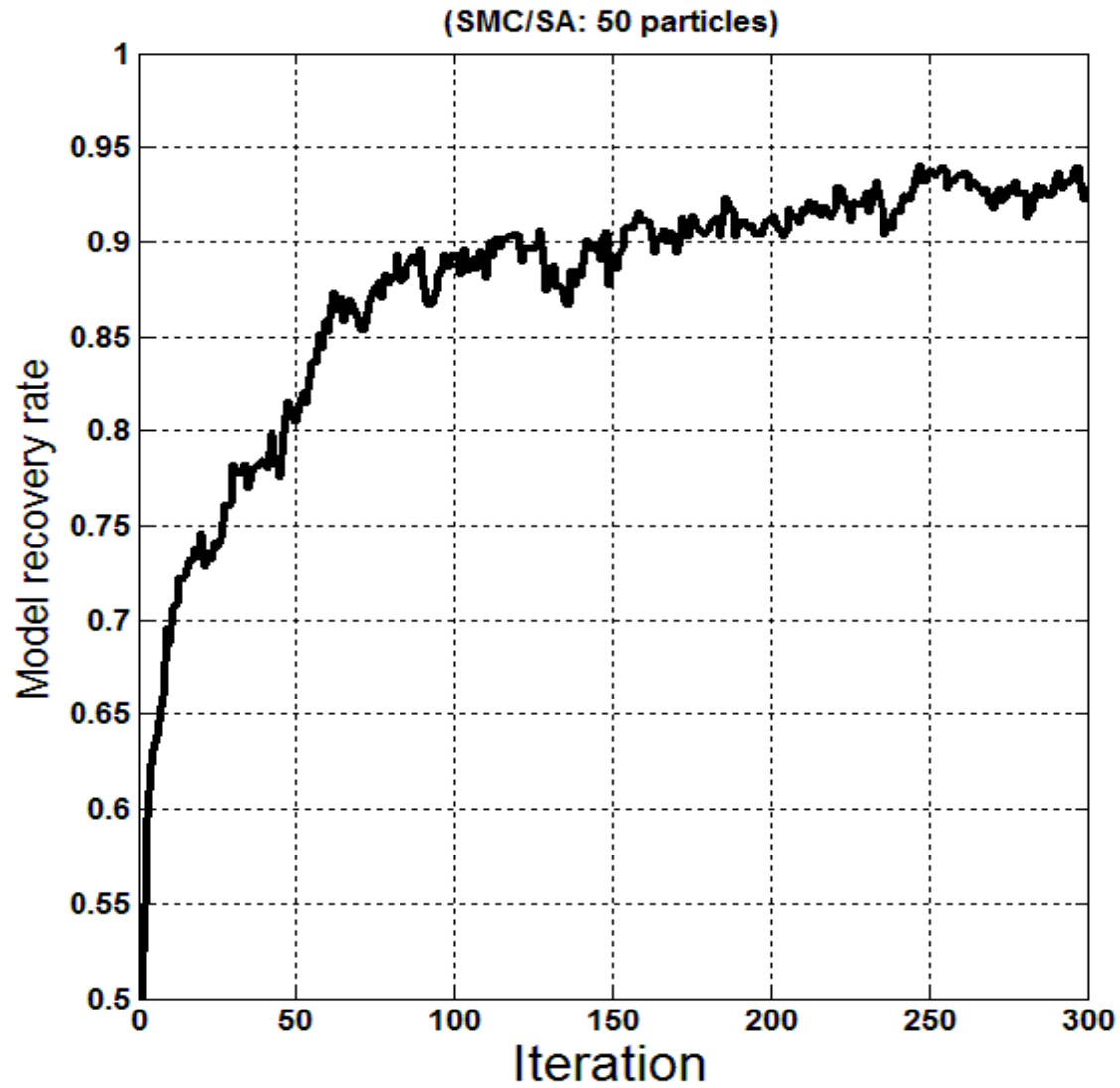
where

$$I_A(d) = 1 \quad \text{if } MDL_A < MDL_B \\ = 0 \quad \text{otherwise}$$

with

$$MDL = -\ln f(y | \hat{\theta}) + \frac{k}{2} \ln \left(\frac{n}{2\pi} \right) + \ln \int \sqrt{|l(\theta)|} d\theta$$

Typical Run of SMC/SA Algorithm



How Good Are the “Optimal” Designs?

N	Type	Design (chosen time intervals)	Model discriminability (% model recovery)
3	Linear	(1, 2, 3)	58.3

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5	Linear	(1, 2, 3, 4, 5)	65.3
	Geometric	(1, 2, 4, 8, 16)	76.5

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	W&E (1991)	(2.5, 5, 10, 20, 40)	79.2

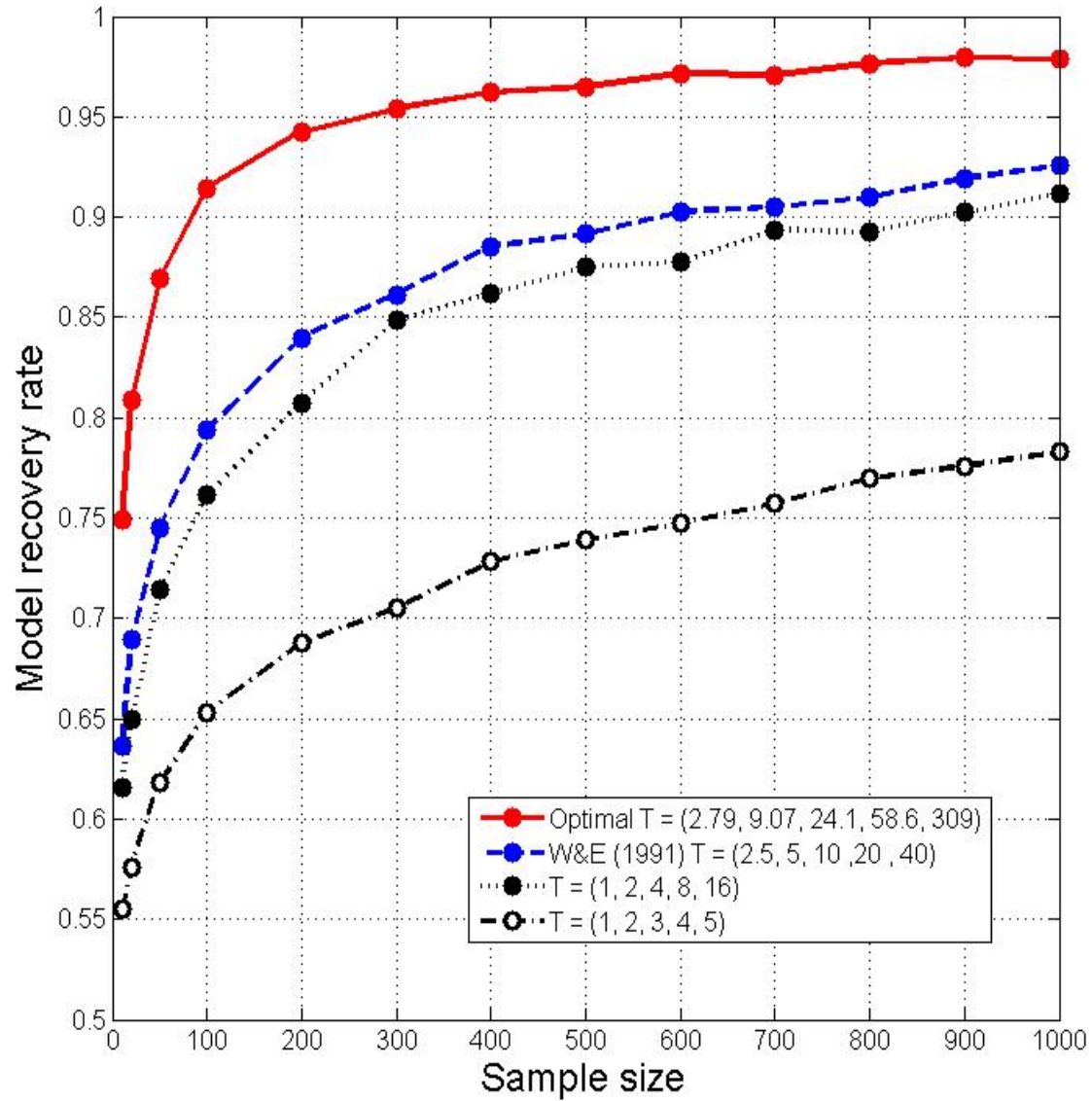
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	Optimal	(2.79, 9.07, 24.1, 58.6, 309)	91.5

- DO found a design that outperforms the W&E design by more than 10% (**91.5%** vs **79.2%**)

- DO found solutions with three time points that are even better than the five time-point design of Wixted & Ebbesen (**86.3%** vs **79.2%**)

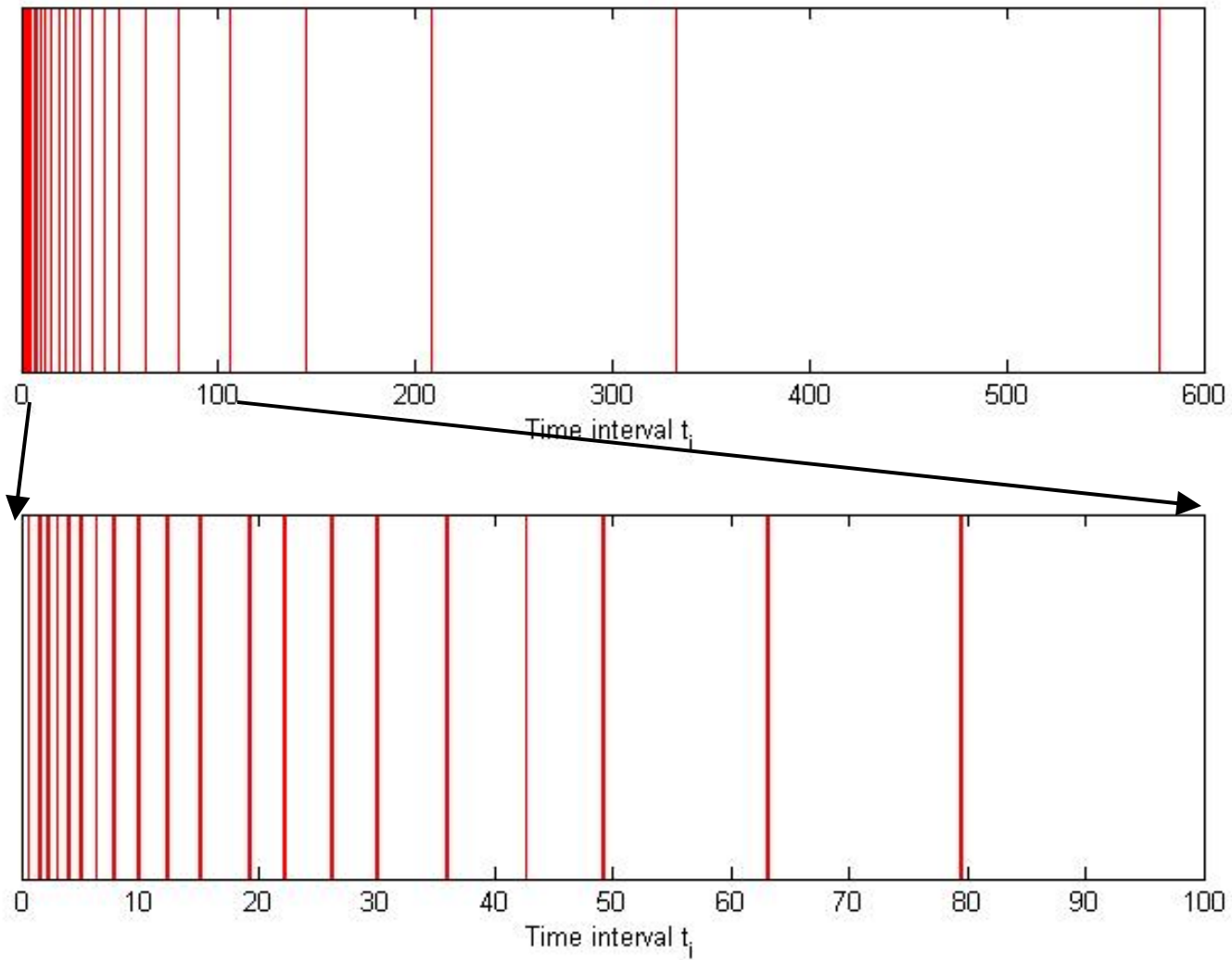
“Power Curves” of Designs



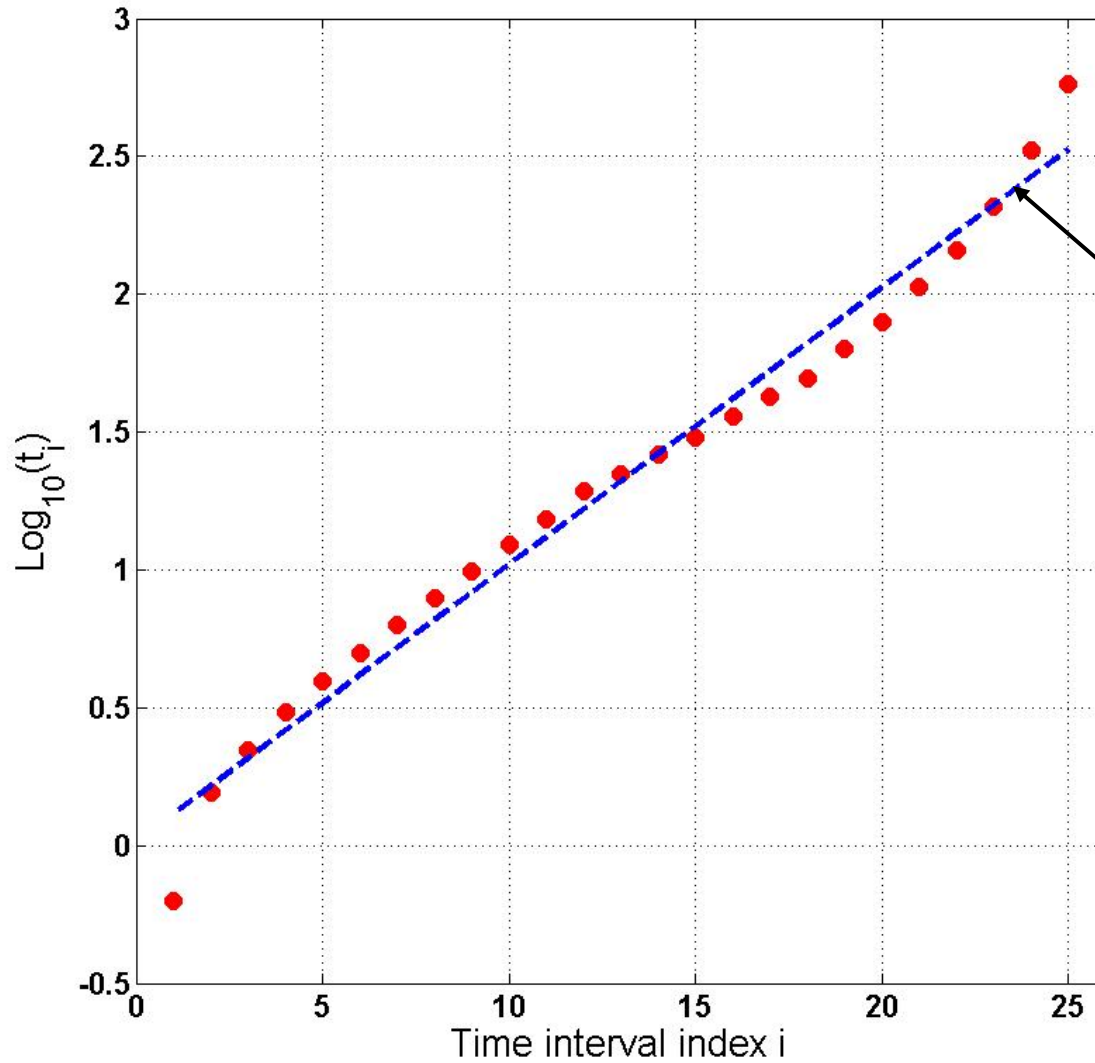
How Good Are the “Optimal” Designs?

N	Type	Design	%Recovery
3	Comparison	(1, 2, 3)	58.3
	Comparison	(1, 2, 4)	61.9
	Optimal	(9.53, 26.9, 252)	86.3
5	Comparison	(1, 2, 3, 4, 5)	65.3
	Comparison	(1, 2, 4, 8, 16)	76.5
	W&E (1991)	(2.5, 5, 10, 20, 40)	79.2
	Optimal	(2.79, 9.07, 24.1, 58.6, 309)	91.5
25	Comparison	(1, 2, 3, 4, ..., 24, 25)	87.2
	Optimal	(0.63, 1.56, 2.22, ..., 333, 578)	97.3

25-Time Point Optimal Design

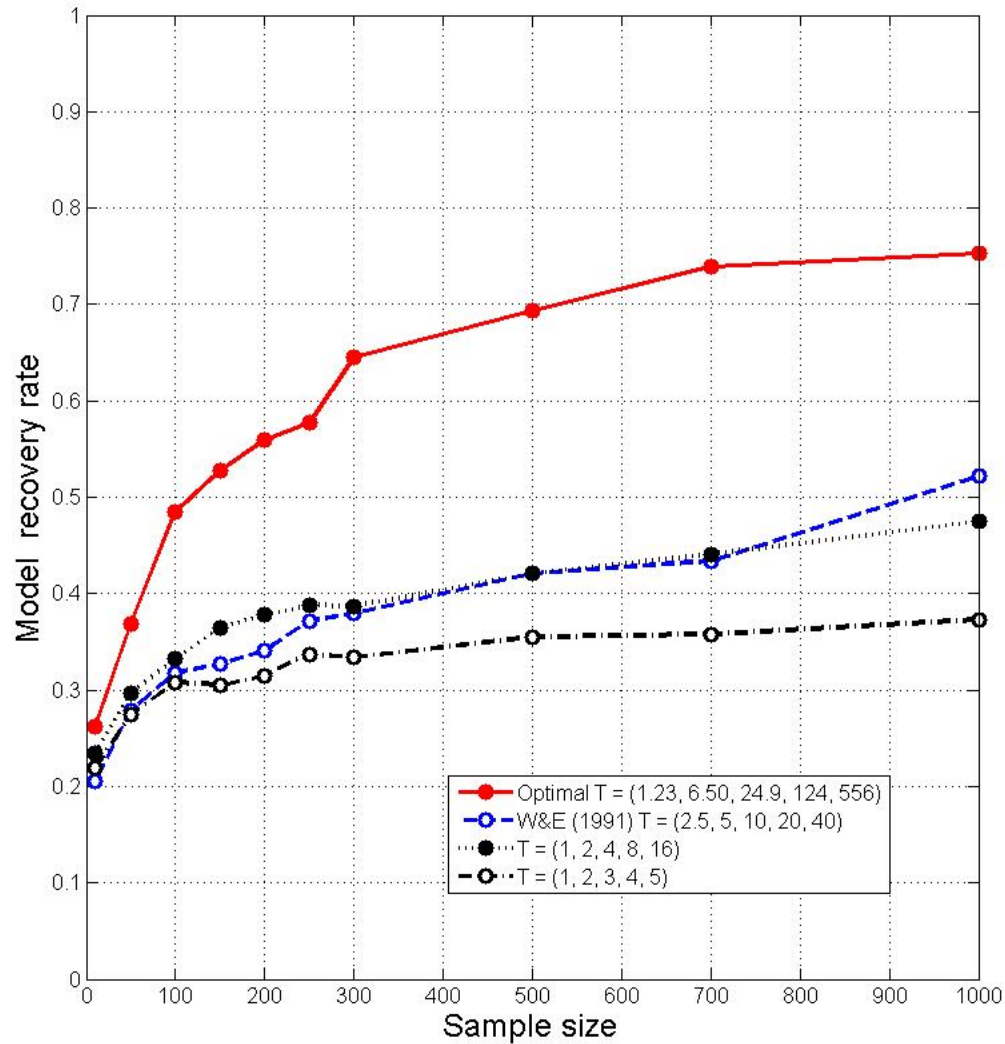


25-Time Point Optimal Design



'geometric' design :
 $t_{i+1} = 1.26 t_i$

Discriminating Six Retention Models



Model	Equation
Power (POW)	$p = a(t + 1)^{-b}$
Exponential (EXP)	$p = ae^{-bt}$
Hyperbolic (HYP)	$p = a/(a + t^b)$
Power with asymptote (POWA)	$p = a(t + 1)^{-b} + c$
Exponential with asymptote (EXPA)	$p = ae^{-bt} + c$
Exponential with exponent (EXPE)	$p = ae^{-bt^c}$

Conclusions

- Design optimization provides a means of
 - identifying experimental designs that are likely to be most successful in discriminating between formal models
- Current work in **adaptive design optimization**
 - Mutual information based utility function
 - Trans-dimensional design optimization using Dirichlet Process

Adaptive Design Optimization (ADO)

- Bayesian **sequential** decision framework
 - Repeat an experiment multiple times
 - Improve the design of the next experiment using knowledge gained from previous experiment

